

# DECODING WITHOUT A DECODER

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## Introduction

### Motivation for GRAND

Digital communications use an error correcting code to recover data transmitted through a noisy channel that causes bit errors. But decoders can require excessive time to decode the data. The recently proposed Guessing Random Additive Noise Decoding (GRAND) algorithm “guesses” the binary noise vector and, after a few attempts, usually produces error-free data. What is exciting about GRAND is that it can “decode” any code. Of people’s special interest are channels that cause errors to come in bursts.

### How GRAND works

```

Inputs:  $Y^n$ , the observed received vector
Outputs:  $\hat{X}, Q$ 

 $d \leftarrow 0, Q \leftarrow 0$ 
while  $d = 0$  do
     $z^n \leftarrow$  the next most likely noise vector
     $Q \leftarrow Q + 1$ 
    if  $Y^n \ominus z^n$  is a code-word then
         $\hat{X} \leftarrow Y^n \ominus z^n$ 
         $d \leftarrow 1$ 
        return  $\hat{X}, Q$ 
    end if
end while
    
```

$$Y^n = X^n \oplus N^n$$

**Traditional decoder:**  
identify  $X^n$  using the structure of code-book.

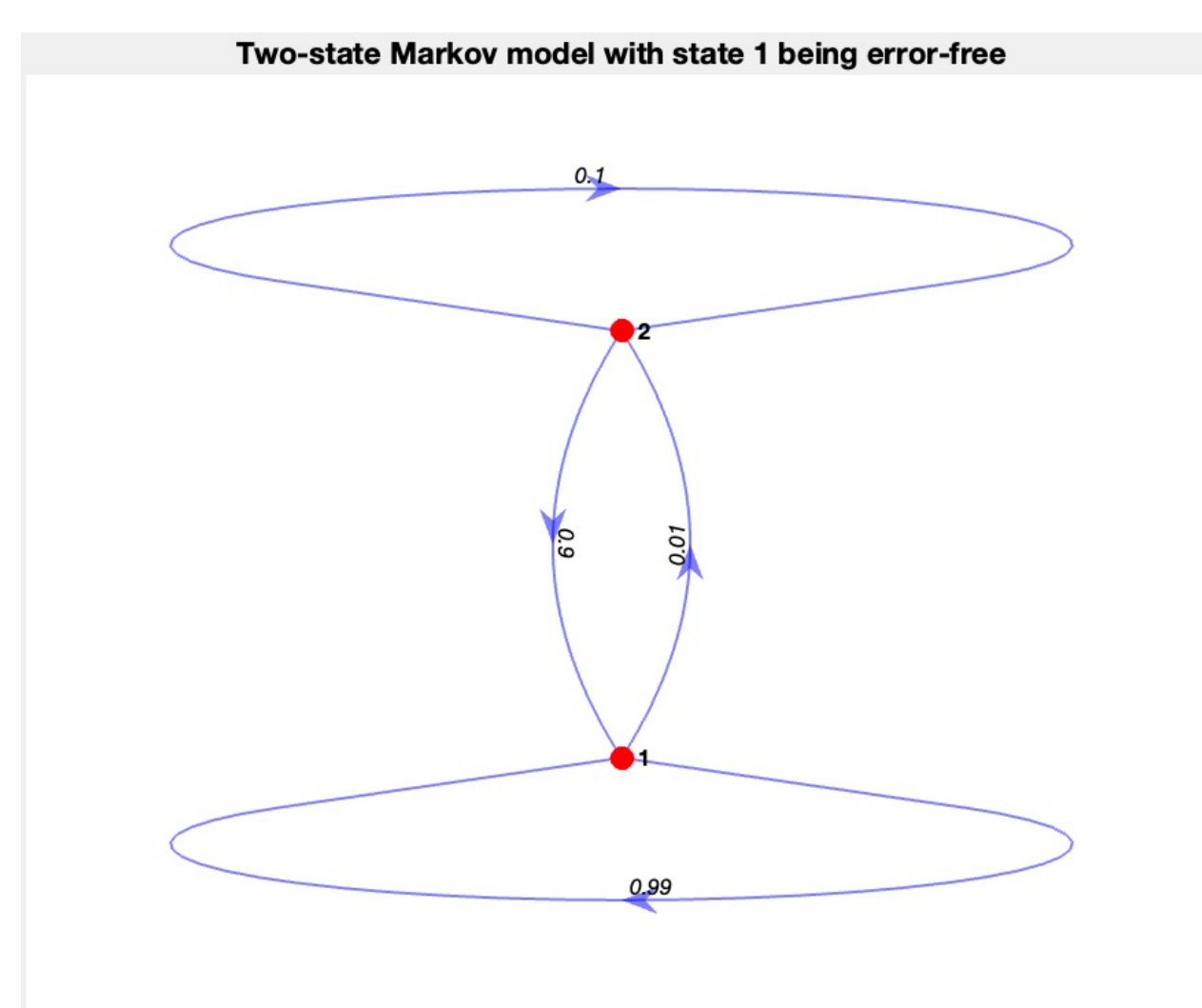
**GRAND:**  
identify  $N^n$  by exploiting structure of channel noise.

### Two conundrums of GRAND that our work hopes to solve:

- Model the channel noise in a way that stays true to the bursty nature of a physical channel.
- Order all noise patterns from the most likely to the least likely.

## Solutions

### Modeling the bursty channel: Two-state Markov Chain



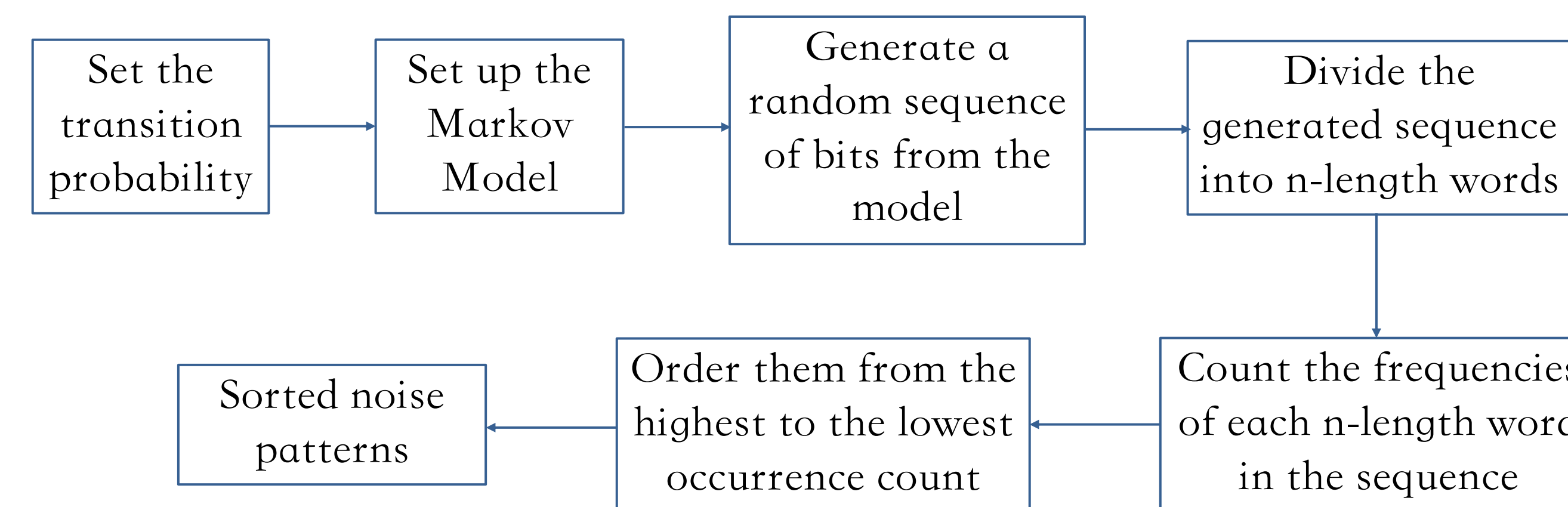
When in the good state, G, the channel is error-free and the corresponding entry in  $N^n$  is to a 0, and when the channel is in the bad state, B, there is an error and the corresponding entry in  $N^n$  is to a 1.

The transition probability from G to B is b and from B to G is g. An error burst is a set of consecutive 1s in  $N^n$  with its length following geometry distribution of mean  $1/g$  and variance  $(1-g)/g^2$ .

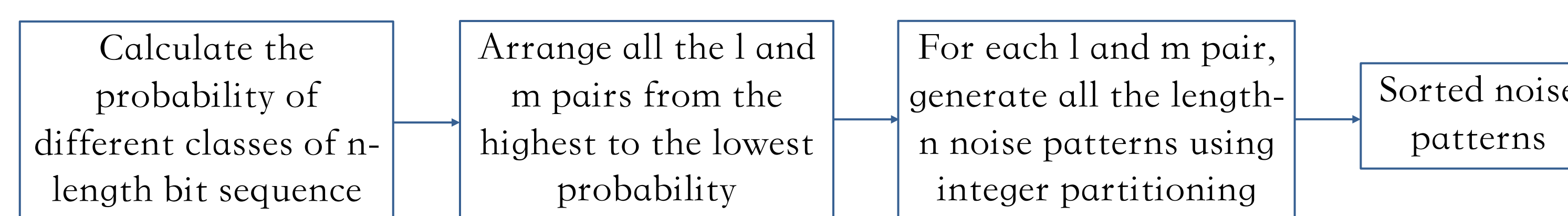
**Constraint**  
Consecutive bursts must be separated by at least one 0.

**Notations**  
l: # 1's in the noise vector.  
m: # bursts of 1's in the noise vector.

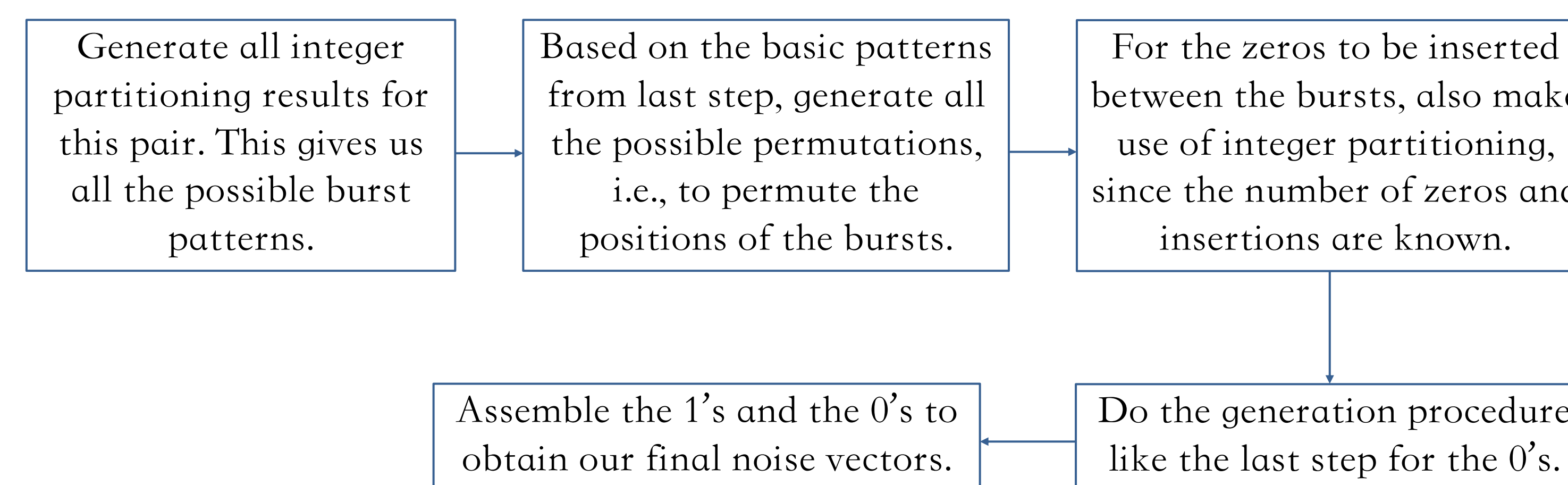
### Approach 1: Using two-state Markov model to find the statistics



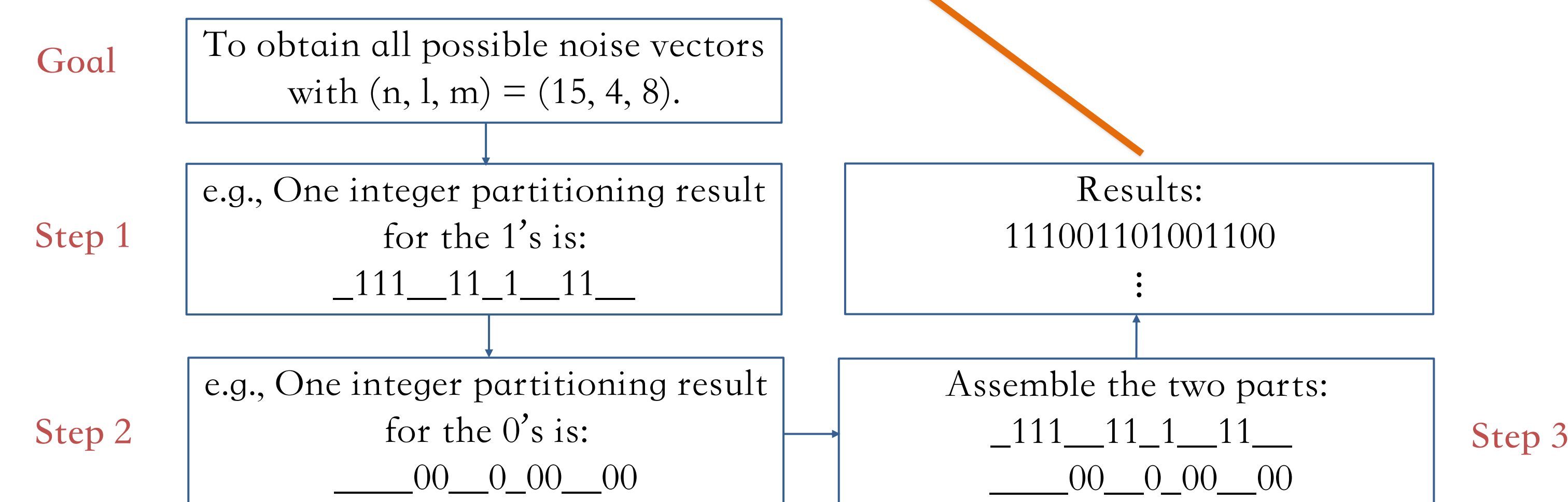
### Approach 2: Calculate probability and apply integer partitioning



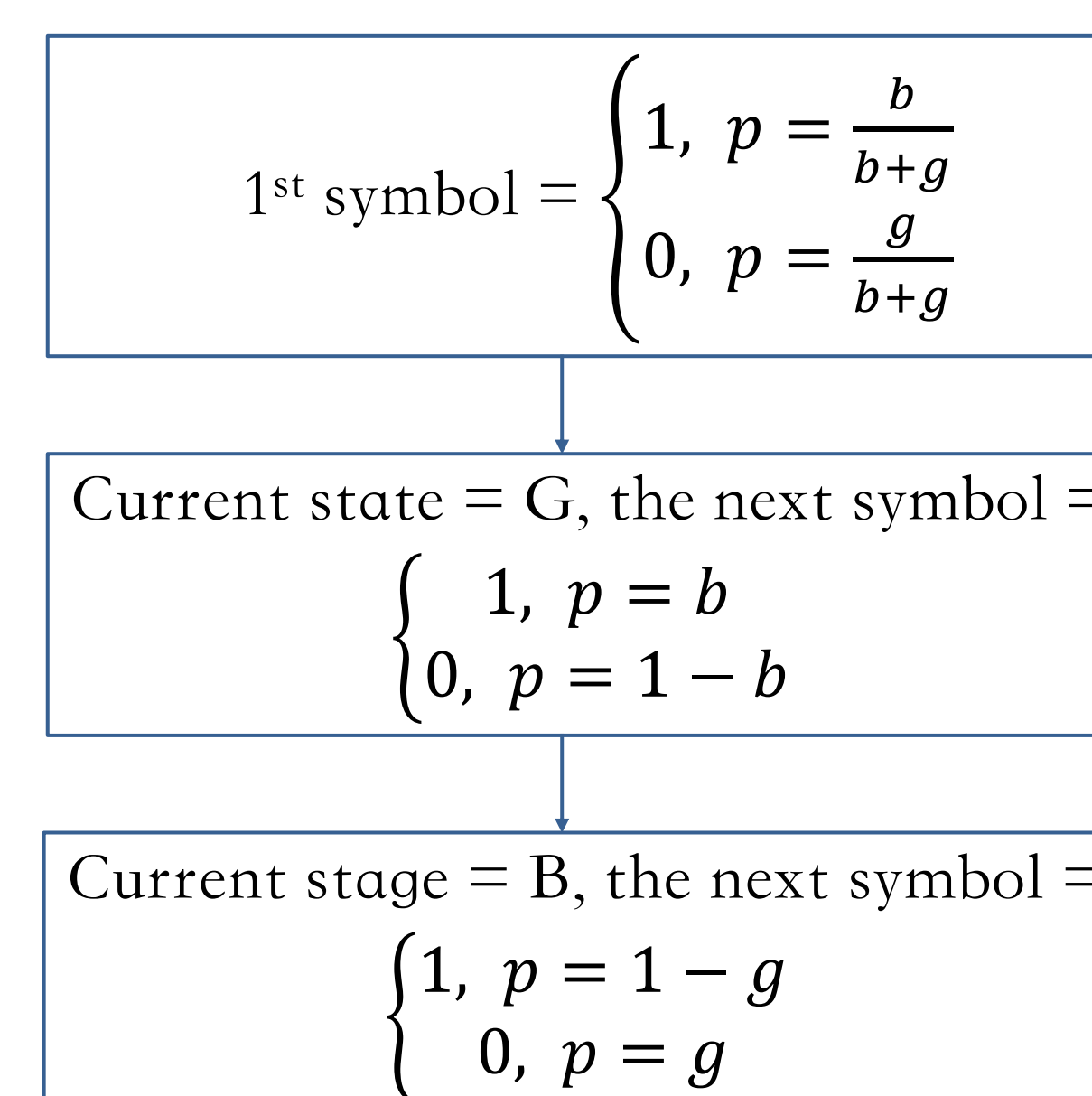
- The algorithm to generate all permutations for a given l and m pair



- Illustration for the algorithm



### Approach 3: Analytical calculation of two-state Markov probability

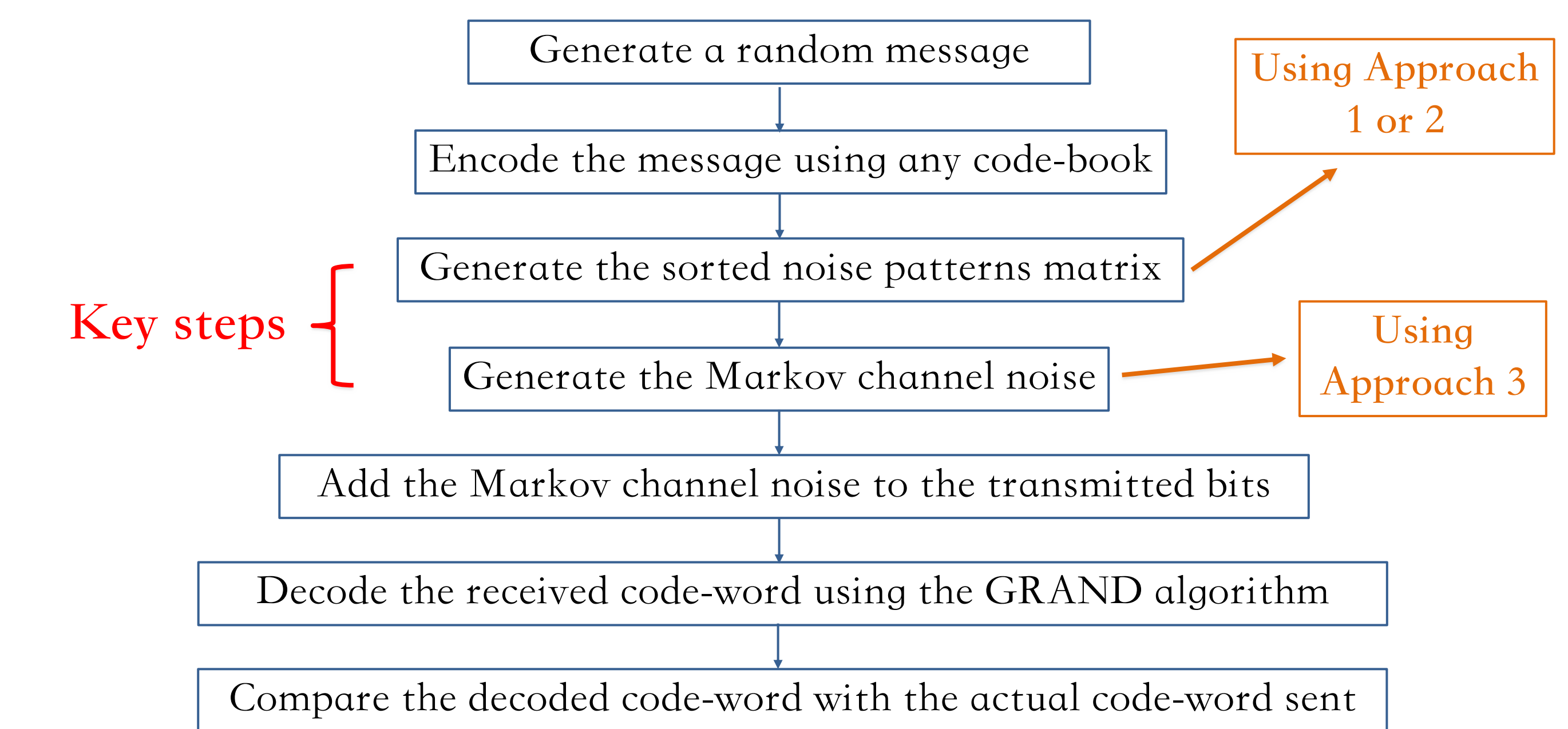


When large length n, calculating every possible sequence using this approach would be intractable.

However, this approach is perfect for generating a “true” noise vector for the GRAND simulation, as we will see in the next section.

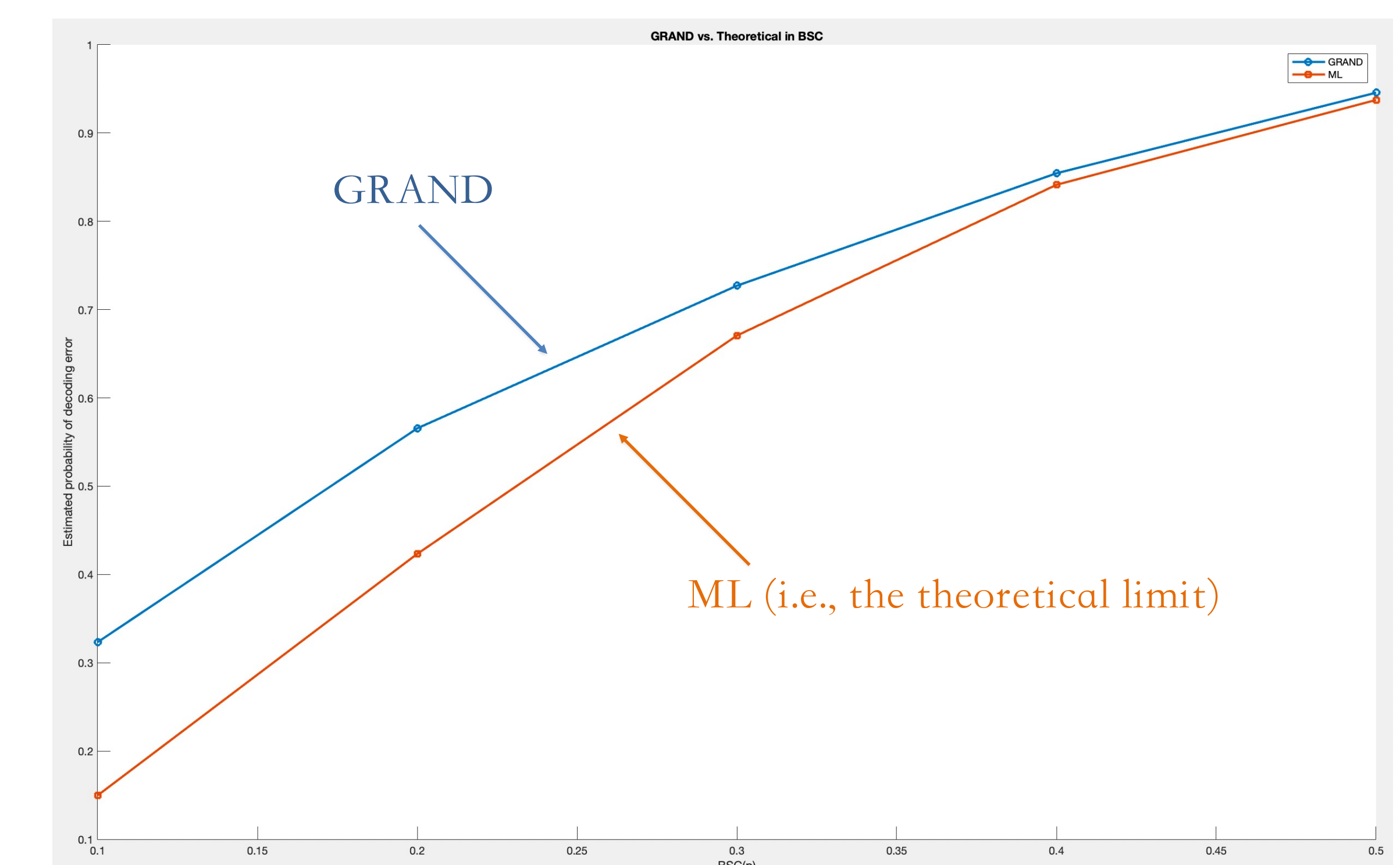
## Results

### Simulation Algorithm

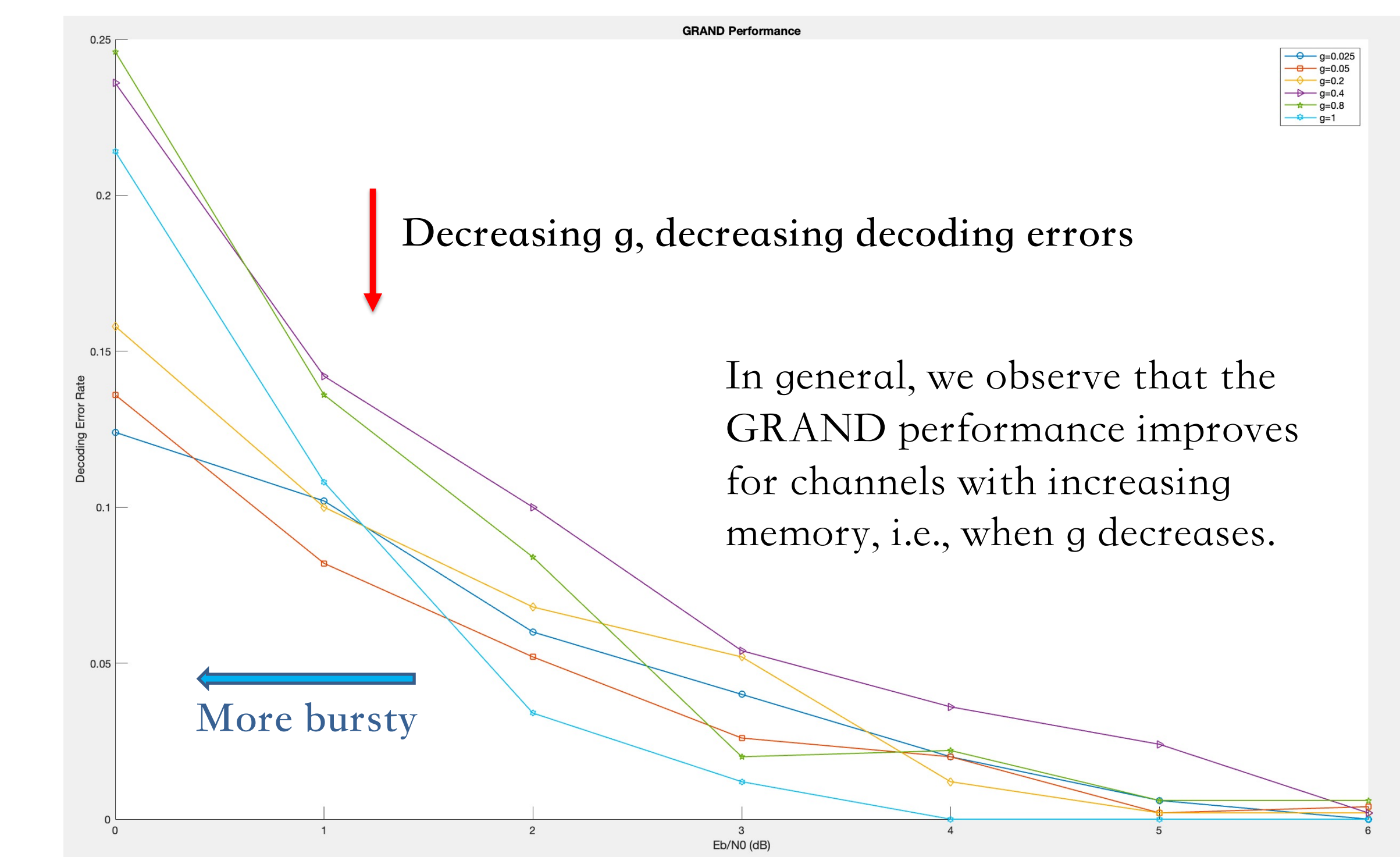


### Simulation Result

- GRAND vs. Theoretical (ML) in an idealized BSC channel



- GRAND performance in a Markov bursty channel



## Reference

Wei An, Muriel Médard, Ken R. Duffy. “Keep the bursts and ditch the interleavers”. IEEE Global Communications Conference, 2020.